



AIR35-2700

**高精度
超长臂展
腕部 IP67**

**High speed
High precision
Ultra-long arm
Wrist IP67**

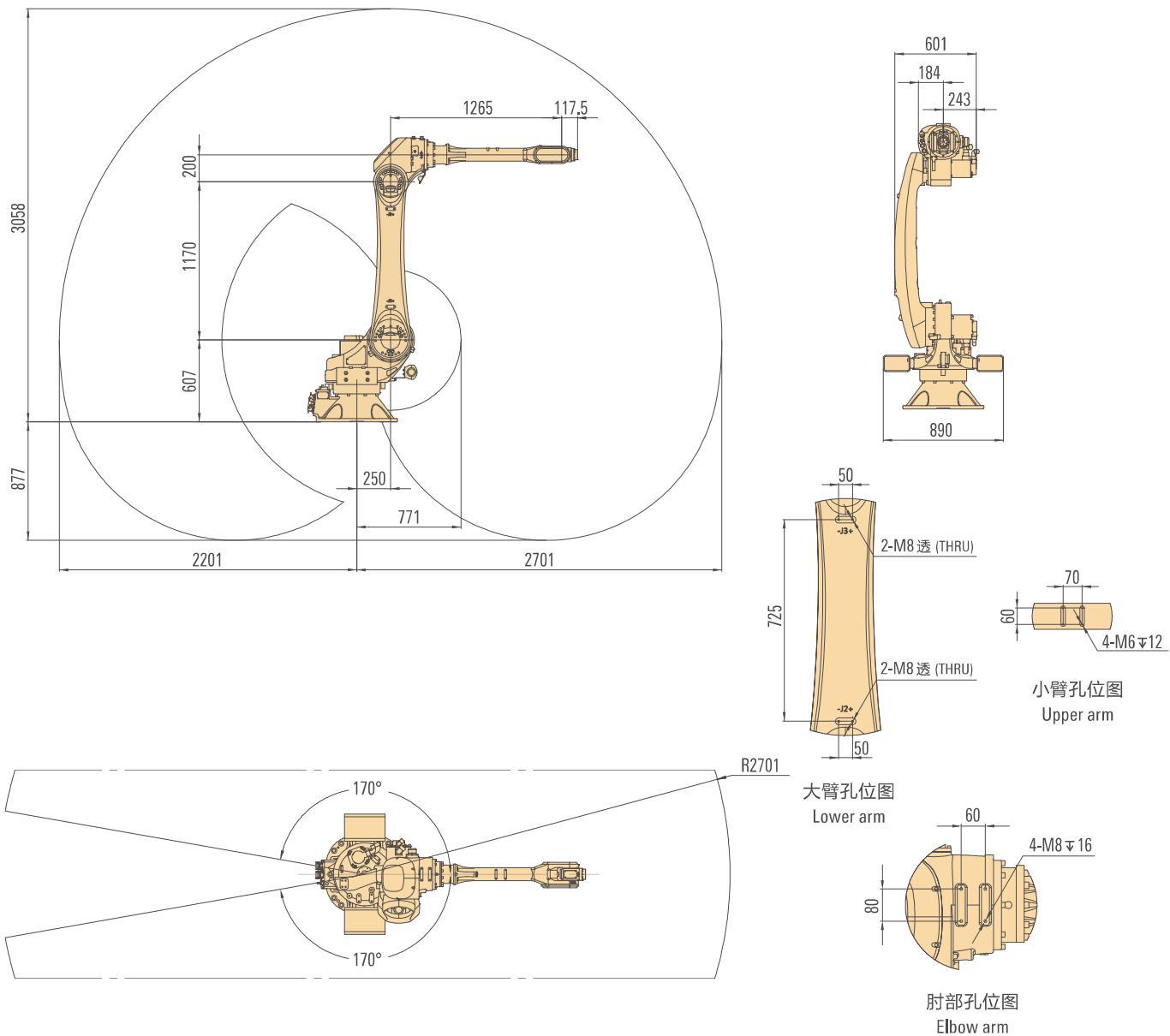
型号 Type		AIR35-2700
轴数 Axes		6
负载 Payload		35kg
机器人本体 Manipulator	重量 Weight	545kg
	最大运动范围 Reach	2701mm
定位精度 Positioning accuracy	位置重复定位精度 Position repeatability	±0.03mm
IP 等级 Ingress Protection		IP54 (腕部 : IP67) IP54 (Wrist : IP67)
安装方式 Mounting		地装 / 吊装 Floor/ ceiling
运动范围 Working range	轴 1* Axis 1 rotation	-170°/+170°
	轴 2 Axis 2 arm	-100°/+100°
	轴 3 Axis 3 arm	-110°/+165°
	轴 4 Axis 4 wrist	-350°/+350°
	轴 5 Axis 5 bend	-125°/+125°
	轴 6 Axis 6 turn	-360°/+360°
运动速度 Rotation rate	轴 1 Axis 1 rotation	185°/s
	轴 2 Axis 2 arm	180°/s
	轴 3 Axis 3 arm	180°/s
	轴 4 Axis 4 wrist	310°/s
	轴 5 Axis 5 bend	375°/s
	轴 6 Axis 6 turn	470°/s
适用控制柜 Controllers		ARC5-280
环境温度: 0~45°C Ambient temperature: 0~45°C 湿度: 恒温下 95% 以内, 无凝露。 Humidity: not more than 95% at constant temperature without condensation.		
安装条件 Mounting conditions 允许高度: 操作机正常工作环境的海拔高度不应超过 1000 米 (在 1000 米 -4000 米高度范围内, 操作机应降额使用) 。 Allowable altitude: not more than 1000m above sea level. 不应有腐蚀性、可燃性、易爆性气体。 No corrosive, flammable or explosive gases.		

* 若去除机械限位, 运动范围可达 -180°/+180°。
If the mechanical limit is removed, the working range can reach -180°/+180°.

- 采用高速、高过载电机, 能量密度高, 力矩波动小, 运行更平稳。
With higher energy density and smaller torque fluctuations, smoother operation can be achieved by using high-speed and high-overload motors.
- 内置气管和IO线束, 有效减少外挂线束对周边设备的干扰。
Built-in air tubes and IO harness, effectively reduces the interference of external wiring harness to peripheral equipment.
- 主要应用于钣金、注塑、陶瓷、建材等行业, 适用于搬运、码垛、点胶等应用场景。
Mainly used in sheet metal, injection molding, ceramics, building materials and other industries, suitable for handling, palletizing, dispensing and other application scenarios.



外形尺寸及运动范围 Outline dimension and Working range



法兰图 Flange drawing

底座安装图 Base installation drawing

