17 AIR4-560B



型号 Type			AlR4-560B
轴数 Axes			6
负载 Payload			4kg
机器人本体 Manipulator	重量 Weight		24kg
	最大运动范围 Reach		560mm
定位精度 Positioning accuracy	位置重复定位精度 Position repeatability		±0.02mm
IP 等级 Ir	ngress Prot	ection	IP67
安装方式 Mounting			地装 / 壁装 / 吊装 Floor/ wall/ ceiling
运动范围 Working range	轴 1*	Axis 1 rotation	-170°/+170°
	轴 2	Axis 2 arm	-110°/+120°
	轴 3	Axis 3 arm	-108°/+148°
	轴 4	Axis 4 wrist	-200°/+200°
	轴 5	Axis 5 bend	-120°/+120°
	轴 6	Axis 6 turn	-350°/+350°
运动速度 Rotation rate	轴 1	Axis 1 rotation	450°/s
	轴 2	Axis 2 arm	370°/s
	轴 3	Axis 3 arm	505°/s
	轴 4	Axis 4 wrist	600°/s
	轴 5	Axis 5 bend	560°/s
	轴 6	Axis 6 turn	850°/s
适用控制柜 Controllers			inCube20/ARC5-12
安装条件 Mounting conditions	环境温度: 0~45℃ Ambient temperature: 0~45℃ 湿度: 恒温下 95% 以内,无凝露。 Humidity: not more than 95% at constant temperature without condensation. 允许高度: 操作机正常工作环境的海拔高度不应超过 1000 米(在 1000 米 -4000 米高度范围内,操作机应降额使用)。 Allowable altitude: not more than 1000m above sea level. 不应有腐蚀性、可燃性、易爆性气体。 No corrosive, flammable or explosive gases.		

* 若去除机械限位, 运动范围可达 -180°/+180°。 If the mechanical limit is removed, the working range can reach -180°/+180°.

AIR4-560B

高速度 高精度 高稳定性 小巧、敏捷 高防护等级 High speed
High precision
High stability
Small and Agile
IP67

中空手腕, 6 轴法兰中空设计, 便于腕部布管布线, 非常适合狭小空间内作业。

Axis 6 hollow flange design, which is convenient for piping and wiring on the wrist, very ideal for narrow space operation.

■ IP67 更高防护等级, 适合机床内潮湿、灰尘和油雾等恶劣条件下运行。

Higher protection level of IP67, suitable for operating under harsh conditions such as humidity, dust and oil mist.

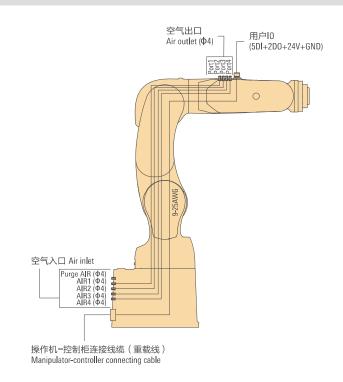
■ 标准循环时间小于 0.33s, 满足追求最短循环时间和最高产量的 雲求。

The standard cycle time is less than 0.33s, meeting your pursuit of the maximum output within the shortest time.

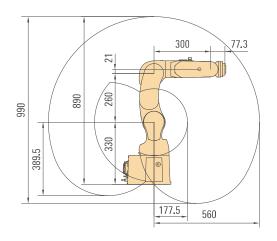
■ 专用的电机散热设计, 轻松应对 3C 行业高强度高频次重复运动产生的高发热。

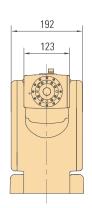
Advanced heat dissipation design of motor, enables AIR4-560B to easily cope with the high heat generated by the high-intensity repetitive operation in the 3C industry.

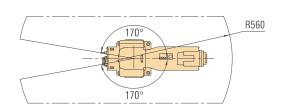
机体内配线 • 配管 Integrated dressing

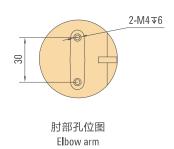


外形尺寸及运动范围 Outline dimension and Working range









法兰图 Flange drawing

底座安装图 Base installation drawing

